



- very rugged
- reliable
- operating temperature up to +140°C
- inductive power supply
- high accuracy
- simple installation



TELEMETRY SYSTEM

for strain gauge measurement on rotating parts

AXON Systems GmbH - Wildmoos 5 - D-82266 Inning a. Ammersee - Germany www.axon-systems.com - info@axon-systems.com Tel.: +49 (0) 8143- 24 198- 0 - Fax: +49 (0) 8143 24 198- 90



he telemetry system AXON J1DB is designed for transmitting strain gauge based measurement signals from rotating shafts under even hardest environments. During operation, a second transmission channel provides information about the inductively provided supply voltage on the rotating part of the system. The quality of the received digital data stream is also displayed via RSSI output. Through this valuable information, all important parameters for operation can be continuously monitored.



Rotor Unit:

Supplies the sensor with highprecision voltage, captures and processes the data from the strain gauge and transmits the fully digitised data stream contactless between the rotating shaft and the Stator Unit.





Control Unit:

The central control unit and data output of the telemetry system. Generates the inductive supply voltage for the rotor unit and reproduces the data measured on the shaft as a voltage signal. Inductive supply and RF data reception are monitored and always controlled during operation to ensure the best possible data transmission.

Stator Unit:

Produces the dynamic inductive field which supplies power to the Rotor Unit on the rotating shaft. Simultaneously it receives the digital data stream from the shaft. Distances up to 70mm between rotor and stator antenna can be realized. Axial and radial relative movements between stator and rotor are covered in an range of several centimeters⁽¹⁾.

(1) Depending on application





The highly effective inductive power supply of the rotating components allows an uninterrupted use even under harsh conditions.

Even in oil, a stable power- and data transmission is ensured.

The distance between the stator and rotor antenna can easily vary between 1 and $70 \text{mm}^{(1)}$.

The intelligent inductive power transmission IPT continuously optimizes the rotor supply voltage during operation.

In addition, the RSSI output⁽²⁾ of the Control Unit provides information about the quality of the received data stream.

Depending on application
Receive Signal Strength Indicator

Strain gauge based measurements on:

- Drive shafts
- Prop shafts
- Torque Flanges
- Rotating gearbox parts
- and many more



The ideal system for torque measurements

The J1DB telemetry system is the perfect foundation for highly professional torque measurement shafts that deliver stable and highly accurate measurement data, even under the toughest conditions. Whether in vehicle testing or on the test bench- AXON telemetry systems standing for reliable measurement results under a wide variety of applications.



Control Unit J1DB-CC All relevant data accesible on CAN bus

In addition to the measurement data, which is available with its own CAN ID and a baud rate of up to 1MBit / s, the system transmits many other useful data in a seperate status ID, such as:

- existing data transmission yes/no
- rotor Vs (level of inductive power supply on rotor)
- device name (freely configurable)
- serial number Control Unit
- serial number currently sending Rotor Unit
- calibration factor for measurement data output in Nm
- offset correction
- channel sample rate

To keep the system quickly accessible and fully flexible, most important values are also available as an analogue voltage signal:

power consumption

less

- measurement values
- rotor Vs (level of inductive power supply on rotor)
- RSSI (received signal strenth indication)

Software configured system settings can be conveniently exported as a .dbc file.

more performance





| | 107557 | 107607 |
|--|--------|--------|

Inductive Power Supply 4.0:

Our new innovative Control Unit features the most efficient inductive power supply:

The active controlled inductive power supply increases the power where necessary but also decreases power when possible.

Thus, power consumption of the entire telemetry system can be decreased by more than 60% for many applications.



Rotor Units

| | Chip Rotor | Flex Rotor | Head Rotor | | | |
|--------------------------------|---|--|--|--|--|--|
| | A A A A A A A A A A A A A A A A A A A | | | | | |
| Туре | J1DB-RD13 | J1DB-RF13 | J1DB-RR13 | | | |
| Signal condidtioning Ch1 | 1 x Strain gaug full bridge | | | | | |
| Signal condidtioning Ch2 | internal measurement of inductive power supply | | | | | |
| Power supply | inductively od battery | | | | | |
| Modulation | PCM (digital) | | | | | |
| ADC | 16 bit | | | | | |
| Measurement rainge | | 0,1 - 500 mV/V adjustable | | | | |
| Carrier frequency (standard) | 13,6 MHz | | | | | |
| Carrier frequency (optionalyl) | 12,6 MHz, 14,6 MHz, 15,6 MHz | | | | | |
| Betriebstemperaturbereich | -40°C +105°C | | | | | |
| Temperature range option T | -40°C +125°C | | | | | |
| Temperature range option H | -40°C +140°C | | | | | |
| minimum bending radius | - | 14 mm | - | | | |
| Housing | Aluminium | without housing; flexible pcb board | without housing; cylindric design | | | |
| Degree of protection | IP67 if the solder contacts are covered accordingly | IP10, electronics painted, cover after application with RTV silicone | IP10, electronics painted, cover after application with RTV silicone | | | |
| Dimensions | 45 x 19 x 7 mm | 98 x 15 x 3,9 mm | Ø19mm x 12mm | | | |
| Weight | 10 grams | 4,5 grams | 3,5 grams | | | |
| Conformity | (6 | | | | | |







Alle Angaben in mm, Toleranz ±0,5mm

Stator Units

Ring Stator Unit

Туре

Specifications

Type of transmission Transmission coil Transmission coil optionally Transmission distance RF-Reception Housing Connections Dimensions (incl. connections) Operating temperature Cable lentgh Stator - Control Unit Weight Degree of protection Conformity (1) Depending on application

| JXD-SR80TE | JXD-SR80HE |
|------------------------------|----------------------------|
| | |
| inductively with conducto | r loop (transmission coil) |
| copper or EMC-stator coil. | IX-ECE02 Ø 40 500mm |
| copper or EMC-stator coil J> | K-ECE02 Ø 300 2000mm |
| 0 80 | mm ⁽¹⁾ |
| wideband (10 N | IHz 30 MHz) |
| aluminium black | powder coated |
| Fischer 4-p | oole, IP68 |
| 67,8 x 53 (bottom p | late 77) x 33,5 mm |
| -40°C +125°C | -40°C +140°C |
| 5m; optional 7m, 8r | n, 10m, 30m, 50m |
| 232 g | rams |
| IPE | 58 |
| C | E |



e-Mobility



recommended accessory

JX-ECE02

Free shapeable transmission coil for Stator Units JX(D)-SRxx**E** with additional EMC-antenna. Length 1m, shortenable

JX-EC01

Free shapeable transmission coil for Stator Units JX(D)-SRxxE. Length 1m, shortenable









Stator Units

Inductiv-Stator without transmission coil



| Тур | JXD-SE60 | JXD-SE60T | |
|-------------------------------|--|---------------|--|
| Type of transmission | inductive as Pick-Up | | |
| RF-Reception | wideband (10 MHz | 30 MHz) | |
| Housing | PTFE | | |
| Transmission distance | 0 60 mm ⁽¹⁾ | | |
| Dimensions (without cable) | 70 x 50 x 35 mm | | |
| Operating temperature | -40°C +105°C | -40°C +125°C | |
| Cable lentgh Stator - Control | 5m; optional 7m, 8m, 1 | .0m, 30m, 50m | |
| Unit | any cable length up to 200m on request | | |
| Weight | 220 grams | | |
| Degree of protection | IP68 | | |
| Conformity | CE | | |
| | | | |

(1) Depending on application





dimensions in mm, tolerances ±0,5mm

Control Unit

Controller CC / CAN with analogue- and CAN-Bus output

Controller CE with analogue output





| | J1DB-CC13-10 | J1DB-CC13-05 | J1DB-CE13-10 | J1DB-CE13-05 |
|------------------------------------|--|-----------------------------------|-------------------------------------|---------------|
| nension | 187 x 105 x 54mm (incl. connectors) | | 205 x 105 x 35mm (incl. connectors) | |
| ight | 740 grams | | 580 grams | |
| oply Voltage | 9 - 36 VDC | | 9 - 36 VDC | |
| ver consumption, typically | 12 VA | | 20 VA | |
| dwarefilter analogue output | 1000 Hz (-3d | В) | 1000 Hz (-3dB) | 500 Hz (-3dB) |
| nal output Rotor Vs ⁽¹⁾ | Phoenix 4-pol, 0-10V, factor 3:1 | | BNC, 0-10V, factor 3:1 | |
| I-Output ⁽²⁾ | Phoenix 4-pol | | , 0-4,5V | |
| id rate | 1 MBit/s | 500kBit/s | | |
| innel sampling rate | 50 - 1550 Hz, selectable in 50Hz-steps | | | |
| nal outputs analog | Strain gauge measurement s RSSI ⁽²⁾ | signal, Rotor Vs ⁽¹⁾ , | | |
| nection socket CAN | LEMO FGG.0B. | 305 | | |
| 1al output CAN-Bus | Measurement data strain gauge [selectively V or Nm ⁽³⁾], Rotor-Vs ⁽¹⁾ , Ready on/off, Control Unit serial number, Rotor Unit serial number, offset correction value, device name, channel sample rate | | | |
| set adjustment analogue | | ±0,5V, per | poti | |
| alogue output measurement nal | | BNC, ±10 | V | |
| rier frequency (standard) | 13,6 MHz | | | |
| rier frequency (optionally) | 12,6 MHz, 14,6 MHz, 15,6 MHz | | | |
| nal delay (analogue) | 1,3 ms | | | |
| eless shunt calibration | released by push button on Control Unit | | | |
| gree of protection | IP40 | | | |
| erating temperature | -20°C - +75°C | | | |
| ervoltage protection | integrated | | | |
| verse polarity protection | integrated | | | |
| oformity | | CE | | |
| upply voltage Rotor Unit | | | | |

Specifications

Тур

Din We Sup Ρον Har Sigr RSS Ваι Cha Sig

Cor Sig

Off Ana sigr Car Car Sig Wir Deg Ope Ove Rev

Cor

(1) S

(2) Receive Signal Strength Indicator

(3) Calibration values for torque output can be stored on the device



The product is in compliance with the requirements of the following European directive:

199/5/EC Radio and Telecommunications Terminal Equipment (R&TTE)

Restriction of the use of certain hazardous substances in electrical and electronic equipment (RoHS) 2011/65/EU

The compliance with the requirements of the European Directive was proved by the application of the following harmonized standards: R&TTE:

RoHS:

EN 300 330.2 V1.5.1 EN 301 4584 V1.9.2 EN 301 4585 V1.9.2 EN 5034-2010 EN 55011:2006 + A11.2008 + A12.2011 + A12.2016 + A11.2008 + A12.2011 + A12.2013 EN 50581:2012

The object of the declaration described above is in conformity with Directive 2011/65/EU of the European Parliament and of the Council of 8 June 2011on the restriction of the use of certain hazardous substances in electrical and electronic equipment.

Another focus of AXON is the production of customized torque- and temperature measurment installations on shafts, flanges, and many other rotating components. Careful planning includes the preparation of release drawings, which allow the user to check all dimensions and details of the final installation.

The flexibility of the AXON telemetry systems enables the construction of installations that work even in the most difficult space conditions.

Sensors and electronics are seald in multiple layers. A highstrength glass fiber composite protects the application from water, oil and mechanical damage. Thus, the maintenancefree applications are ideally suited for long-term driving tests.







The flexible design options of the AXON telemetry systems allow countless application variants.







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From development to customized solutions all from one hand

Development and production
Application of measurement shafts
Strain gauge application and calibration









Whether by phone, e-mail or in personour support is always available for questions about our systems - fast and easy!

Our experienced engineers and technicians will be happy to assist you in planning your measurement taskscontact us!

Contents and illustrations of this datasheet have been elaborated to the best of our knowledge and with utmost diligence we reserve the right of error and technical modifications.

AXON Systems GmbH - Wildmoos 5 - 82266 Inning a. Ammersee - Germany www.axon-systems.com - info@axon-systems.com Tel.: +49 (0) 8143- 24 198- 0 - Fax: +49 (0) 8143 24 198- 90